

# **XRD64L43**

## Dual 10-Bit 40MSPS CMOS ADC

July 2003

### **FEATURES**

- 10-Bit Resolution
- Two Monolithic Complete 10-Bit ADCs
- 40 MSPS Conversion Rate
- On-Chip Track-and-Hold
- On-Chip Voltage Reference
- Low 5 pF Input Capacitance
- TTL/CMOS Outputs
- Tri-State Output Buffers
- Single +3.0V Power Supply Operation
- Low Power Dissipation: 200mW-typ @ 2.7V
- Power Down Mode Less Than 5mW
- 75dB Crosstalk (fin=1.0MHz)
- -40°C to +85°C Operation Temperature Range

### **APPLICATIONS**

- Medical Imaging
- Instrumentation
- **Data Aquisition Systems**
- **Digital Comunications**

### **BENEFITS**

- Reduction of Components
- Reduction of System Cost
- High Performance @ Low Power Dissipation
- Long Term Time and Temperature Stability

### **GENERAL DESCRIPTION**

The XRD64L43 is two 10-bit, monolithic, 40 MSPS ADCs. Manufactured using a standard CMOS process, the XRD64L43 offers low power, low cost and excellent performance. The on-chip track-and-hold amplifier(T/H) and voltage reference (VREF) eliminate the need for external active components, requiring only an external ADC conversion clock for the application. The XRD64L43 analog input can be driven with ease due to the high input impedance.

The design architecture uses 17 time-interleaved 10bit SAR ADCs in each converter to achieve high conversion rate of 40 MSPS minimum. In order to insure and maintain accurate 10-bit operation with respect to time and temperature, XRD64L43 incorporates an auto-calibration circuit which continuously adjusts and matches the offset and linearity of each ADC. This auto-calibration circuit is transparent to the

user after the initial 4.2ms calibration (168,000 initial clock cycles).

The power dissipation is only 200 mW at 40 MSPS with +2.7V power supply.

The digital output data is straight binary format, and the tristate disable function is provided for common bus interface.

The XRD64L43 internal reference provides cost savings and simplifies the design/development. The output voltage of the internal reference is set by two external resistors. The internal reference can be disabled if an external reference is used for a power savings of 50 mW.

### ORDERING INFORMATION

Part Number Package Type		Temperature Range
XRD64L43AIV	64-Lead LQFP	-40°C to +85°C

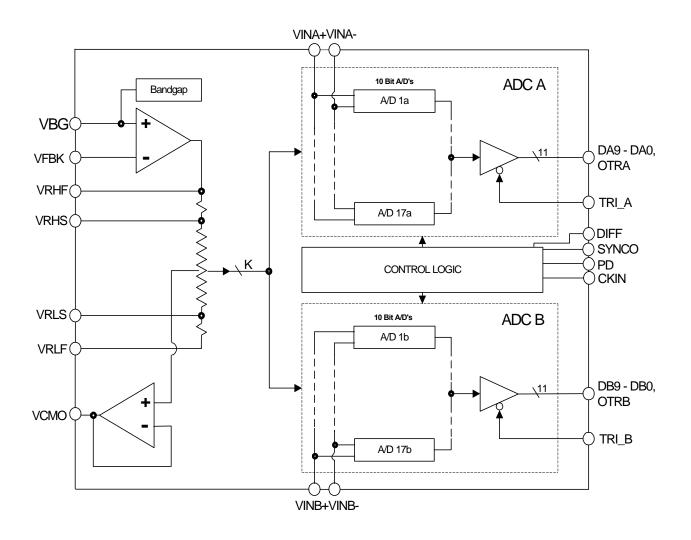
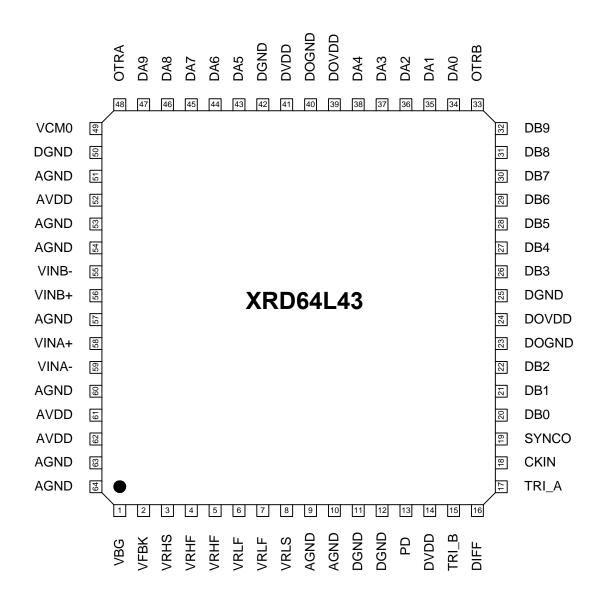


Figure 1. XRD64L43 Simplified Block Diagram







### **PIN DESCRIPTION**

Pin #	Symbol	Description
1	VBG	Bandgap Voltage Output
2	VFBK	Analog Reference Feedback
3	VRHS	Top Voltage Reference Sense
4	VRHF	Top Voltage Reference Force
5	VRHF	Top Voltage Reference Force
6	VRLF	Bottom Voltage Reference Force
7	VRLF	Bottom Voltage Reference Force
8	VRLS	Bottom Voltage Reference Sense
9	AGND	Analog Ground
10	AGND	Analog Ground
11	DGND	Digital Ground
12	DGND	Digital Ground
13	PD	Power Down, Active High
14	DVDD	Digital Supply Voltage
15	TRI_B	Tri-state for the B Channel Outputs, Active High
16	DIFF	Hi=Differential Mode, Lo=Single-Ended Mode
17	TRI_A	Tri-state for the A Channel Outputs, Active High
18	CKIN	Clock Input
19	SYNCO	Data Valid Output (Rising Edge)
20	DB0	Digital Output Bit 0 (LSB) ADC B
21	DB1	Digital Output Bit 1 ADC B
22	DB2	Digital Output Bit 2 ADC B
23	DOGND	Digital Output Ground
24	DOVDD	Digital Output Supply Voltage
25	DGND	Digital Ground
26	DB3	Digital Output Bit 3 ADC B
27	DB4	Digital Output Bit 4 ADC B
28	DB5	Digital Output Bit 5 ADC B
29	DB6	Digital Output Bit 6 ADC B
30	DB7	Digital Output Bit 7 ADC B
31	DB8	Digital Output Bit 8 ADC B
32	DB9	Digital Output Bit 9 (MSB) ADC B
33	OTRB	Over Range Digital Output Bit ADC B
34	DA0	Digital Output Bit 0 (LSB) ADC A
35	DA1	Digital Output Bit 1 ADC A
36	DA2	Digital Output Bit 2 ADC A
37	DA3	Digital Output Bit 3 ADC A
38	DA4	Digital Output Bit 4 ADC A
39	DOVDD	Digital Output Supply Voltage
40	DOGND	Digital Output Ground
41	DVDD	Digital Supply Voltage



## PIN DESCRIPTION (CONT'D)

Pin #	Symbol	Description
42	DGND	Digital Ground
43	DA5	Digital Output Bit 5 ADC A
44	DA6	Digital Output Bit 6 ADC A
45	DA7	Digital Output Bit 7 ADC A
46	DA8	Digital Output Bit 8 ADC A
47	DA9	Digital Output Bit 9 ADC A
48	OTRA	Over Range Digital Output Bit ADC A
49	VCMO	Differential Common Mode Voltage Output
50	DGND	Digital Ground
51	AGND	Analog Ground
52	AVDD	Analog Supply Voltage
53	AGND	Analog Ground
54	AGND	Analog Ground
55	VINB-	Analog Input B(-)
56	VINB+	Analog Input B(+)
57	AGND	Analog Ground
58	VINA+	Analog Input A(+)
59	VINA-	Analog Input A(-)
60	AGND	Analog Ground
61	AVDD	Analog Supply Voltage
62	AVDD	Analog Supply Voltage
63	AGND	Analog Ground
64	AGND	Analog Ground



Test Conditions (Unless Otherwise Specified)

 $T_A = 25^{\circ}C$  AV<sub>DD</sub> = DV<sub>DD</sub> = +3.0V, VIN = GND to +2.5V,  $V_{RLF} = GND$ ,  $V_{RHF} = +2.5V$  and Fs = 40 MSPS, 50% Duty **Cycle, Differential Input Mode** 

Symbol	Parameter	Min.	Тур.	Max.	Unit	Conditions
DC ACCURA	CY					
DNL	Differential Non-Linearity	-0.75	+/-0.25	0.75	LSB	
INL	Integral Non-Linearity		+/-0.5		LSB	
MON	Monotonicity		No Mi	ssing Codes		Guaranteed by Test
FSE	Full Scale Error		<u>+</u> 10		mV	Note 1
ZSE	Zero Scale Error		5		mV	Single Ended Mode
ANALOG INP	UT					
INVR	Input Voltage Range	1		VRHS - VRLS	V	VRLF Grounded
INRES	Input Resistance		20		KOhms	
INCAP	Input Capacitance		5		pF	
INBW	Input Bandwidth		400		MHz	-1dB Small Signal
REFERENCE	INPUT, INTERNAL BANDGA	P REFER	ENCE AN	ND REFEREN	CE BUFFER	3
R <sub>LADDER</sub>	Ladder Resistance	100	125	150	Ohms	Note 1
R <sub>SENSE</sub>	Sense Resistance		2		Ohms	
RLADTCO	Ladder Resistance Tempco		+0.8		Ohms/°C	
VBG	Bandgap Output Voltage Range	1.15	1.25	1.35	V	
VBGTC	Bandgap Reference Tempco		30		ppm/°C	
VRLF		0.0	0.0	2.0	V	
VRHF		VRLF+ 1.0		AVdd-0.3	V	Internal Reference Buffer
VRHF	External Reference	VRLF+ 1.0	2.5	AVdd	V	External
VRHF PSRR	Internal Reference Buffer		6		mV/V	
VCMO, Comr	non Mode Voltage		<b>.</b>	, ,		1
VCMO	Common Mode Voltage	1.15	1.25	1.35	V	
Isource	Current Source	200	500		uA	

### Notes:

Full Scale ADC reference is VRHS - VRLS.

**Test Conditions (Unless Otherwise Specified)** 

 $T_A = 25^{\circ}C$  AV<sub>DD</sub> = DV<sub>DD</sub> = +3.0V, VIN = GND to +2.5V,  $V_{RLF} = GND$ ,  $V_{RHF} = +2.5V$  and Fs = 40MSPS, 50% Duty Cycle, Differential Input Mode

Symbol	Parameter	Min.	Тур.	Max.	Unit	Conditions
DYNAMIC PE	RFORMANCE Fs = 40MHz					
SNR	Signal-to-Noise Ratio					Not Including Harmonics
	fin = 1.0 MHz	58	60		dB	
	fin = 4.0 MHz	57	60		dB	
	fin = 10.0 MHz	57	59		dB	
SINAD	Signal-to Noise and Distortion					Including Harmonics
	fin = 1.0 MHz	58	60		dB	
	fin = 4.0 MHz	57	59		dB	
	fin = 10 MHz	56	58		dB	
ENOB EFFE	CTIVE NUMBER OF BITS				•	
	fin = 1.0 MHz	9.3	9.7		Bit	
	fin = 4.0 MHz	9.2	9.5		Bit	
	fin = 10 MHz	9.0	9.2		Bit	
SFDR SPURI	OUS FREE DYNAMIC RANG	E				
SFDR	fin = 1.0 MHz		70		dB	
Crosstalk	fin = 1.0 MHz		75		dB	
IMD	fin <sub>1</sub> = 2.5 MHz		70		dB	Intermodulation Distortion
	fin <sub>2</sub> = 3.5 MHz					
CONVERSIO	N AND TIMING CHARACTE	RISTICS (	C <sub>L</sub> = 10pF	)		1
MAXCON	Maximum Conversion	40	50		MSPS	
MINCON	Minimum Conversion		100		KSPS	
Lat	Latency		17		cycles	Guaranteed by Design
APJT	Aperture Jitter Time		12		ps	Peak-to Peak
t <sub>r</sub>	Digital Output Rise Time		3		ns	
t <sub>f</sub>	Digital Output Fall Time		3		ns	
<sup>t</sup> pd	Output Data Propagation Delay		6	25	ns	
<sup>t</sup> den	Output Data Enable Delay		6	20	ns	Guaranteed by Design
<sup>t</sup> dis	Output Data Disable Delay		5	20	ns	Guaranteed by Design
CLKDC	Clock Duty Cycle	40	50	60	%	Guaranteed by Design



Test Conditions (Unless Otherwise Specified)

 $T_A = 25^{\circ}C$  AV<sub>DD</sub> = DV<sub>DD</sub> = +3.0V, VIN = GND to +2.5V,  $V_{RLF} = GND$ ,  $V_{RHF} = +2.5V$  and Fs = 40 MSPS, 50% Duty Cycle, Differential Input Mode

Symbol	Parameter	Min.	Тур.	Max.	Unit	Conditions	
DIGITAL INPUTS							
DVINH	Digital Input High Voltage	2.5			V		
DVINL	Digital Input Low Voltage			0.5	V		
DIINH	Digital Input High Leakag	e					
CKIN	Clock Input	-1.0	0.05	1.0	μΑ		
DIFF	Differential/Single-Ended	-1.0	-0.25	1.0	uA	Internal pull-up resistor	
	Input						
TRI_A/TRI_B	A/B Channel Tri-State	-125.0	-90.0	-50.0	uA	Internal pull-down resistor	
PD	Power Down	-125.0	-90.0	-50.0	uA	Internal pull-down resistor	
DIINL	Digital Input Low Leakag	e					
CKIN	Clock Input	-5.0	0.05	5.0	nA		
DIFF	Differential/Single-Ended	50.0	90.0	125.0	uA	Internal pull-up resistor	
	Input						
TRI_A/TRI_B	A/B Channel Tri-State	-1.0	0.25	1.0	uA	Internal pull-down resistor	
PD	Power Down	-1.0	0.25	1.0	uA	Internal pull-down resistor	
DINC	Digital Input capacitance		5	8	pF		
DIGITAL OUTF	PUTS (CL = 10 pF)						
DOHV	Digital Output High	DVdd	DVdd-		V	IOH = 1.5 mA	
	Voltage	-0.4V	0.3V				
DOLV	Digital Output Low		0.3	0.4	V	IOL = 1.5 mA	
	Voltage						
IOZ	High-Z Leakage	-100	0.2	100	nA		

Test Conditions (Unless Otherwise Specified)

 $T_A = 25^{\circ}C$  AV<sub>DD</sub> = DV<sub>DD</sub> = +3.0V, VIN = GND to +2.5V,  $V_{RLF} = GND$ ,  $V_{RHF} = +2.5V$  and Fs = 40 MSPS, 50% Duty Cycle, Differential Input Mode

Symbol	Parameter	Min.	Тур.	Max.	Unit	Conditions	
POWER SUPF	POWER SUPPLIES						
AV <sub>DD</sub>	Analog Power Supply Voltage	2.7	3.0	3.3	V		
DV <sub>DD</sub>	Digital Power Supply Range	2.7	AV <sub>DD</sub>	3.3	V	$DV_{DD} = AV_{DD}$	
Fs = 40 MHz,	$\overrightarrow{AV}_{DD} = \overrightarrow{DV}_{DD} = 2.7V, CL = 10$	pF, Fin = 1	0MHz (Inc	ludes Iref (	Current)		
AIDD	Analog Supply Current		55		mA		
DIDD	Digital Supply Current		13		mA		
DOIDD	Output Driver Current		6		mA		
PDISS	Power Dissipation		200		mW		
Fs = 40 MHz,	$AV_{DD} = DV_{DD} = 3.3V$ , $CL = 10$	pF, Fin = 1	0MHz (Inc	ludes Iref (	Current)		
AIDD	Analog Supply Current		37	70	mA		
DIDD	Digital Supply Current		15	20	mA		
DOIDD	Output Driver Current		15	20	mA		
PDISS	Power Dissipation		225	365	mW		
POWER DOWN CURRENT							
IPD	Power Down Current		100	300	μΑ		

## ABSOLUTE MAXIMUM RATINGS ( $T_A = +25^{\circ}$ C unless otherwise noted)<sup>1, 2, 3</sup>

V <sub>DD</sub> to GND	+7.0V	Lead Temperature (Sold	ering 10 seconds)300°C
$V_{RT}\&V_{RR}$	V <sub>DD</sub> +0.5 to GND -0.5V	Maximum Junction Tem	perature150°C
	V <sub>DD</sub> +0.5 to GND -0.5V	Package Power Dissipati	ion Ratings (T <sub>A</sub> =+70°C)
	V <sub>DD</sub> +0.5 to GND -0.5V	TQFP	$\theta_{JA} = 89.4$ °C/W
	V <sub>DD</sub> +0.5 to GND -0.5V	ESD	2000V min
Storage Temperature	65°C to 150°C		

### Notes:

- Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation at or above this specification is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability.
- Any input pin which can see a value outside the absolute maximum ratings should be protected by Schottky diode clamps from input pin to the supplies. All inputs have protection diodes which will protect the device from short transients outside the supplies of less than 100mA for less than 100ms.
- $V_{DD}$  refers to  $AV_{DD}$  and  $DV_{DD}$ . GND refers to AGND and DGND



### APPLICATION SECTION

### **Voltage References**

The top ladder voltage for the XRD64L43 can be provided from an internal bandgap reference. The bandgap reference and its feedback path, Pins 1 and 2 respectively, can be used to set the voltage for VRHF. Select Rf and Ri (if gain is necessary) so that VRHF=VBG(1+Rf/Ri). The internal bandgap voltage is 1.24 volts. The XRD64L43 has a low impedence ladder, therefore, the typical value for Rf and Ri is 10K (Rf and Ri are recommended to be greater than 5K). See Figure 2. for a simplified diagram. Decoupling caps on the sense inputs to AGND should be used to reduce injectioin of high-frequency noise.

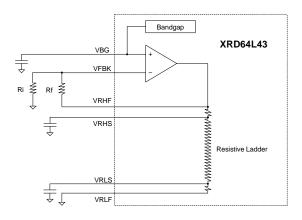


Figure 2. Voltage Reference Generated from the Internal Bandgap Voltage w/gain

External voltage references can be forced at VRHF and VRLF. If VRHF and VRLF are driven externally, VFBK should be connected to AVdd, which tri-states the bandgap reference. Direct inputs or inputs driven by external amplifiers can be used to drive the ladder reference voltages of the XRD64L43. See Figure 3. for a simplified diagram. The sense inputs are intended for sensing purposes only and care must be taken to insure that no current flow be present in the sense lines.

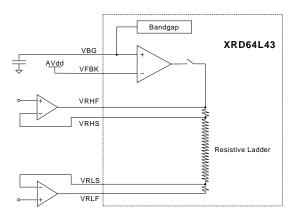


Figure 3. Voltage Reference Provided by an External Source as Direct Inputs

### Single-Ended Inputs

The XRD64L43 can be used in either single-ended or differential input mode. For differential inputs, see the Differential Inputs Section. Single-ended inputs minimize the amount of external components necessary to interface with the XRD64L43. The common inputs, VINA(-) and VINB(-) should be tied to ground. VINA(+) and VINB(+) can be used to apply direct inputs to the XRD64L43. Figure 4. is a simplied diagram for singleended inputs. Pin 16, DIFF should be held low to select single-ended inputs.

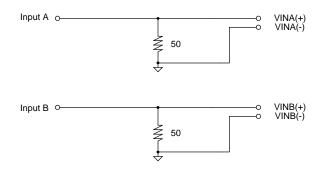


Figure 4. Single-Ended Inputs for the XRD64L43

### **Differential Inputs**

The XRD64L43 can be used in either differential or single-ended input mode. For single-ended inputs, see the Single-Ended Inputs Section. Differential inputs reduce system noise by removing noise components common at both input pins. Figure 5. is a simplified diagram that is used as a common test circuit with our XRD64L43ES application board. This circuit is used to evaluate the dynamic performance of the XRD64L43 using differential inputs. Pin 16, DIFF should be held high to select differential inputs.

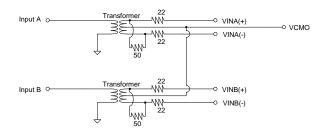


Figure 5. Common Test Circuit for the **Differential Input Mode** 

### SYNCO, Data Valid Delay and Latency

SYNCO is an output pin provided by the XRD64L43. Valid data is available on the rising edge of SYNCO. see Figure 6. The Latency for the XRD64L43 is 17 clock cycles.

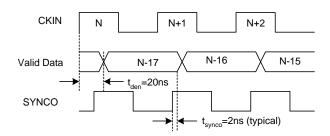


Figure 6. SYNCO, Data Valid Delay and Latency for the XRD64L43

## **Auto-Calibration**

The XRD64L43 incorporates an auto-calibration circuit which continuously adjusts and matches the offset and linearity of each ADC. This auto-calibration circuit is transparent to the user after the initial 4.2ms calibration (168,000 initial clock cycles).

Note: To avoid auto-calibration after power down, do not disable CKIN. CKIN can be slowed down significantly to save power without losing calibration.



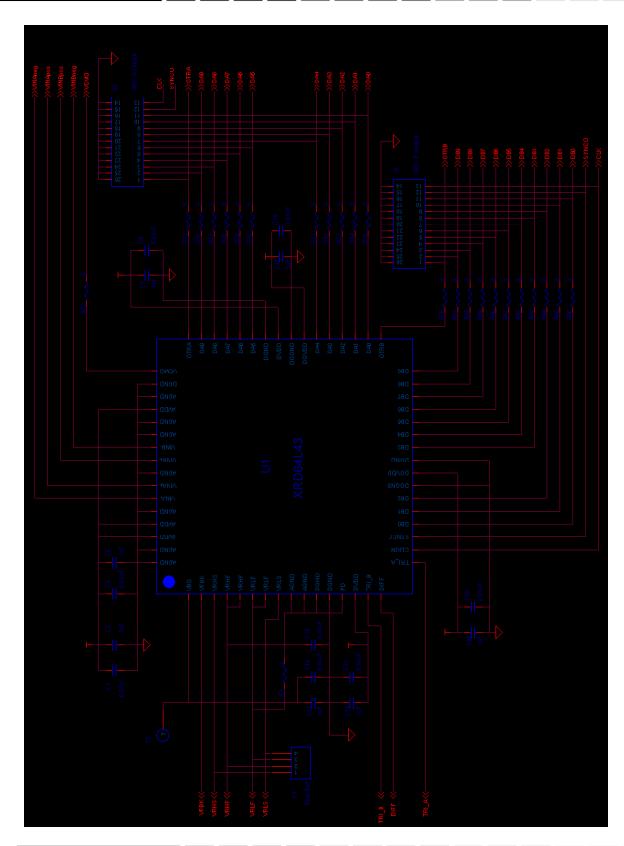
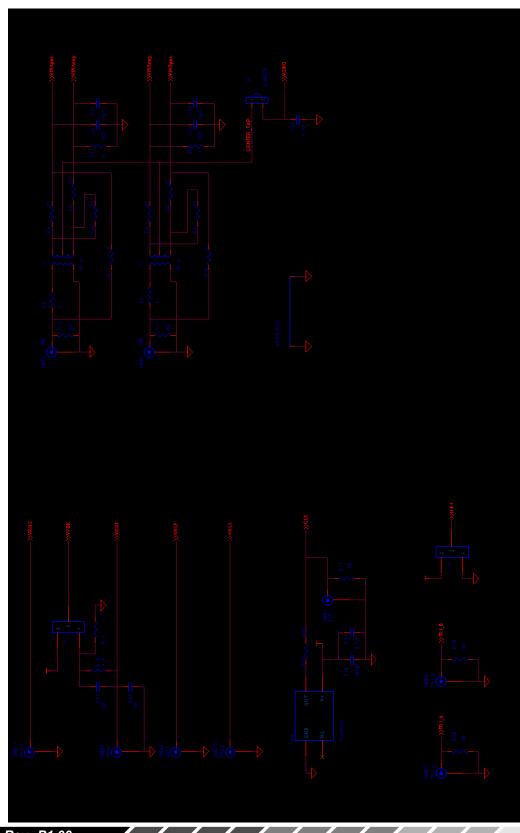


Figure 7a. XRD64L43ES-Application Circuit for the XRD64L43



Rev. P1.00



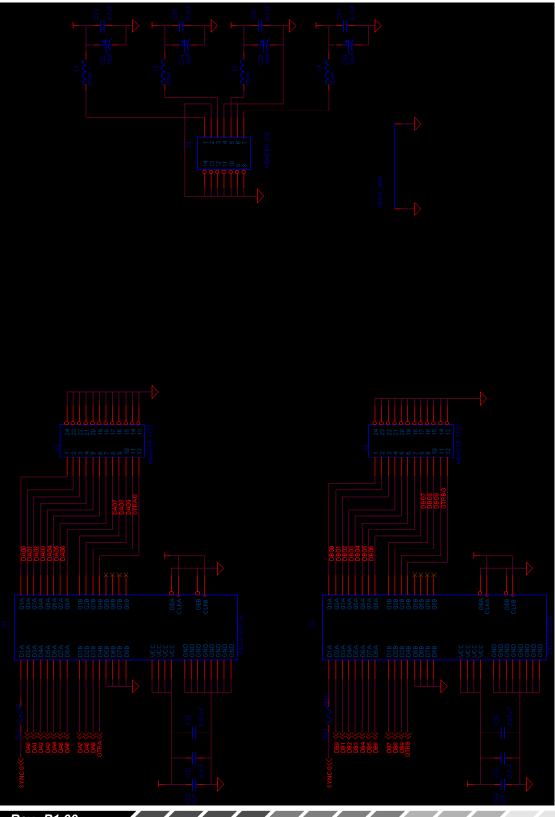


Figure 7c. XRD64L43ES-Application Circuit for the XRD64L43

Rev. P1.00

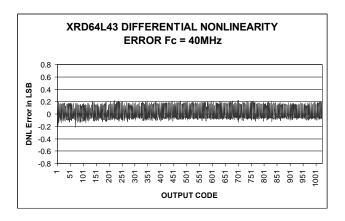


Figure 8. Differential Non-Linearity, Differential Input Mode, Fc=40MHz, Fin=1.5kHz, VRHF=2.5V,  $V_{DD}=3V$ 

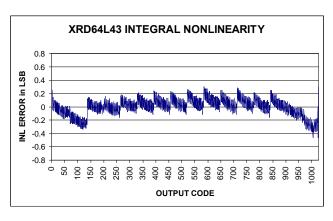


Figure 9. Integral Non-Linearity, Differential Input Mode, Fc=40MHz, Fin=1.5kHz, VRHF=2.5V,  $V_{DD}=3V$ 

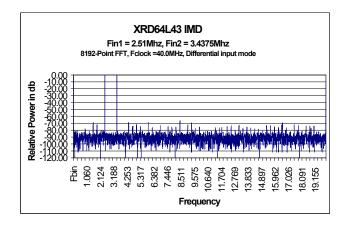


Figure 10. Intermodulation Distortion, Fin1=2.51MHz, Fin2=3.4375MHz, 8192-point FFT, Fc=40MHz, Differential Input Mode

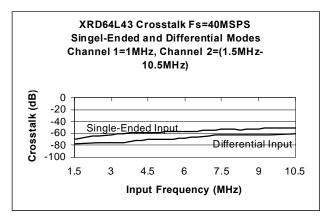


Figure 11. Crosstalk vs Input Frequency, V<sub>DD</sub>=3V, Differential and Single Ended Inputs



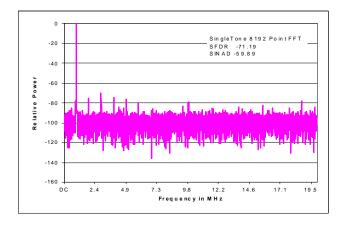


Figure 12. FFT Spectrum @Fclock = 40.0MHz, Fin = 1.0MHz, DIFFERENTIAL INPUT MODE

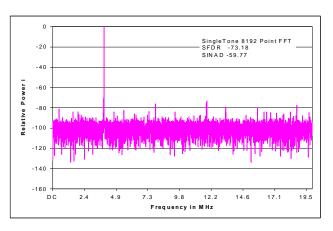


Figure 13. FFT Spectrum @Fclock = 40.0MHz, Fin = 4.0MHz, DIFFERENTIAL INPUT MODE

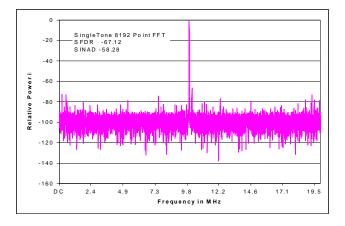


Figure 14. FFT Spectrum @Fclock = 40.0MHz, Fin = 10.0MHz, DIFFERENTIAL INPUT MODE

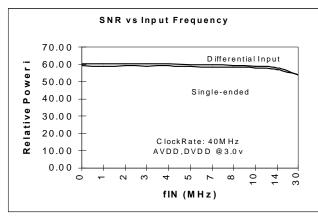


Figure 15. SNR vs Input Frequency, Differential and Single Ended Inputs, V<sub>DD</sub>=3V

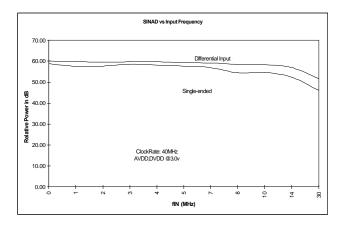


Figure 16. SINAD vs Input Frequency, Differential and Single Ended Inputs,  $V_{DD}=3V$ 

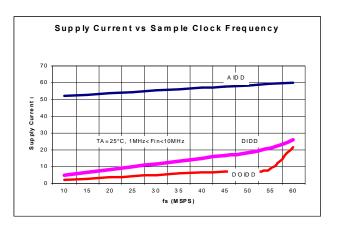


Figure 17. Supply Current vs Sample Clock Frequency

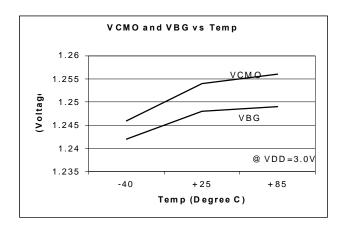


Figure 18. VCMO and VBG vs Temperature

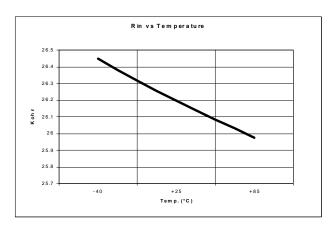
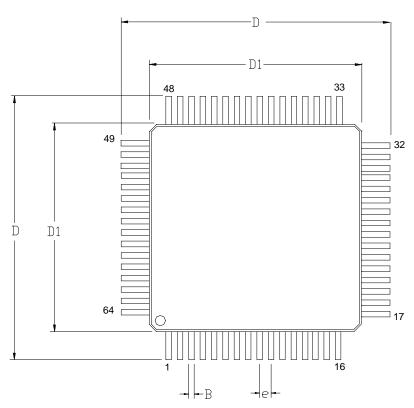


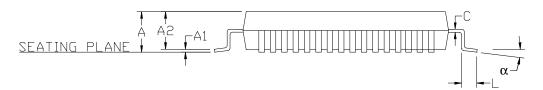
Figure 19. Rin of VINA+, VINB+ vs Temperature at Fc=40MSPS



## 64 LEAD LOW-PROFILE QUAD FLAT PACK (10 mm x 10 mm X 1.4 mm LQFP, 1.0 mm Form)

Rev. 3.00





Note: The control dimension is in millimeters.

	INC	HES	MILLIN	IETERS
SYMBOL	MIN MAX		MIN	MAX
Α	0.055	0.063	1.40	1.60
A1	0.002	0.006	0.05	0.15
A2	0.053	0.057	1.35	1.45
В	0.007	0.011	0.17	0.27
С	0.004	0.008	0.09	0.20
D	0.465	0.480	11.80	12.20
D1	0.390	0.398	9.90	10.10
е	0.020	BSC	0.50	BSC
L	0.018	0.030	0.45	0.75
α	0°	7°	0°	7°



# **Notes**



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